

# Multi-criteria linear programming with reverse search

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- 2 Reverse search
- 3 Enumeration of efficient solutions without book-keeping

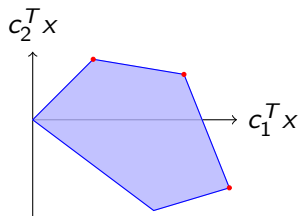
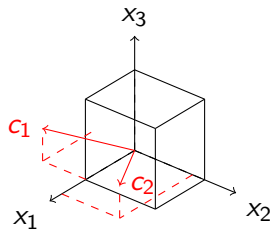
# Multi-criteria linear problem

- Given  $C \in \mathbb{R}^k$ ,  $A \in \mathbb{R}^{m \times n}$ ,  $b \in \mathbb{R}^m$

$$\min / \max Cx$$

$$\text{s.t. } Ax = b$$

$$x \geq 0$$

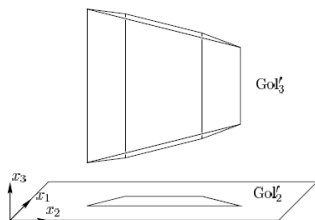


# Preliminaries

- Basis  $B$  is set of  $m$  column indices of  $A$  with corresponding regular matrix  $(A_{B(1)} A_{B(2)} \dots A_{B(m)})$
- Co-basis  $N$  set of non-basic indices
- Pivoting to adjacent basic feasible solution by pivoting non-basic index  $j \in N$  into  $B$
- $x^* \in \mathcal{X}$  efficient solution if and only if there exists  $\lambda \in \mathbb{R}_+^k$  such that  $x^*$  is optimal solution to  $\min / \max \lambda^T Cx$  s.t.  $x \in \mathcal{X}$

# Bi-criteria linear program with $2^{n-1}$ non-dominated vertices based on deformed cube

$$\begin{aligned} & \max(x_{n-1}, x_n) \\ & \text{s.t. } 0 \leq x_1 \leq 1, \\ & \quad \epsilon x_1 \leq x_2 \leq 1 - \epsilon x_1, \\ & \quad \epsilon(x_i - \gamma x_{i-1}) \leq x_{i+1} \leq 1 - \epsilon(x_i - \gamma x_{i-1}) \\ & \quad \text{for } 2 \leq i \leq n, \epsilon < 0.5, \gamma \leq 0.25\epsilon. \end{aligned}$$



Source: "Deformed products and maximal shadows of polytopes" by Amenta, Ziegler

## Conventional graph searches

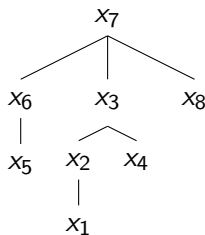
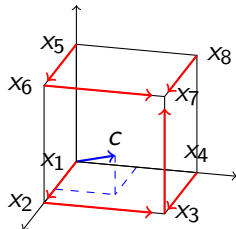
▷ Depth-first-search

```
initialize data structure  $S$   
while  $S$  is not empty do  
   $v \leftarrow S.pop()$ ;  
  if  $v$  is not labeled yet then  
    label  $v$ ;  
    for all  $w$  adjacent to  $v$  do  
       $S.push(w)$   
    end for  
  end if  
end while
```

- Graph searches use datastructure (e.g. stack, priority queue) to keep track of already visited nodes
- Number of elements in data structure might be huge

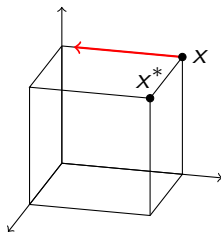
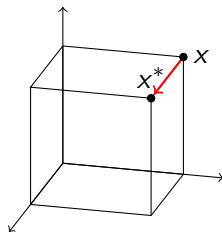
# Reverse search

- Coined by Avis and Fukuda: “Reverse search for enumeration”
- Enumeration of vertices of polyhedra without book-keeping
- Consider paths generated by simplex from any vertex towards optimal vertex
- Paths yield a tree that can be traversed



## Traversing the reverse search tree

- Let  $x^*$  be currently considered vertex with corresponding basis  $B^*$
- Let  $N = \{N(1), \dots, N(n - m)\}$  be set of non-basic indices
- Simulate pivoting  $N(1)$  into  $B^*$  yielding  $B$
- Check whether pivot rule w.r.t. objective  $c$  pivots from  $B$  to  $B^*$ 
  - if yes: pivot  $N(1)$  into  $B^*$
  - if no: neglect  $N(1)$  and check for  $N(2)$
- apply recursively



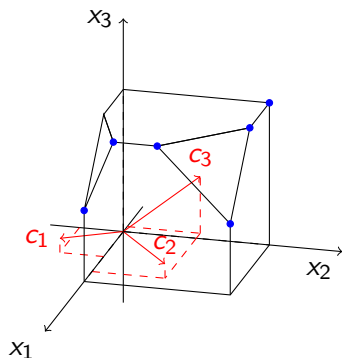


## Pseudo-code for reverse search

```
 $B \leftarrow B^*, N \leftarrow N^*, j \leftarrow 1;$   
repeat  
  while  $j \leq |N^*|$  do  
     $v \leftarrow N(j);$   
    if  $\text{reverse}(B, v, u)$  then;  
       $\text{pivot}(B, v, u);$   
      if  $\text{lexmin}(B, 0)$  then  
        output current vertex;  
      end if  
       $j = 1;$   
    else  
       $j \leftarrow j + 1;$   
    end if  
  end while  
   $\text{selectpivot}(B, r, j);$   
   $\text{pivot}(B, r, N(j));$   
   $j \leftarrow j + 1;$   
until  $j > |N^*| \wedge B == B^*$ 
```

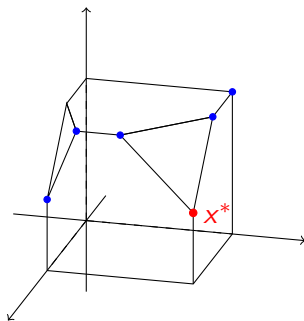
# Enumerate efficient solutions without book-keeping

- Efficient solutions are connected
- Goal: Use reverse search approach for enumerating efficient solutions



# Phase 1

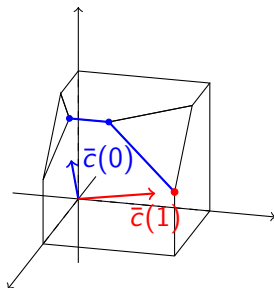
- Compute efficient solution  $x^*$  that acts as root node



- Which scalarisation of  $c_1, \dots, c_k$  shall be used as objective for reverse search?
- Problem: arbitrary but fixed (scalarized) objective might connect efficient solution with non-efficient solution

## The path of the parametric simplex

- Let  $x^*$  be efficient solution computed in Phase 1
- Let  $c^*$  be objective which optimizes  $x^*$
- Let  $x$  be another efficient solution
- Let  $c$  be objective which optimizes  $x$
- Consider  $\bar{c}(\lambda) = \lambda c^* + (1 - \lambda)c$  for  $\lambda \in [0, 1]$



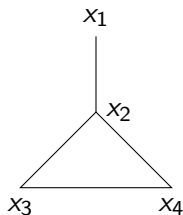
- Path taken by  $\bar{c}(\lambda)$  connects only efficient solutions with  $x^*$  as terminal solution

## Idea: Change considered objective after each step

- Consider  $\bar{c}(\lambda) = \lambda c^* + (1 - \lambda)c$  until first break-point
  - ▶ If  $x \neq x^*$ , then  $x$  is optimal for  $\bar{c}(\lambda)$  for  $\lambda \in [0, \bar{\lambda}]$  with  $\bar{\lambda} < 1$
  - ▶ Some  $\hat{x}$  becomes optimal for  $\bar{c}(\lambda)$  for  $\lambda > \bar{\lambda}$
  - ▶ Let  $\hat{c}$  be objective for which  $\hat{x}$  is optimal
- Change considered objective to  $\lambda c^* + (1 - \lambda)\hat{c}$
- $x^*$  remains terminal solution for  $\lambda = 1$
- In each step parametric objective can be computed from tableau of current basic feasible solution and root tableau

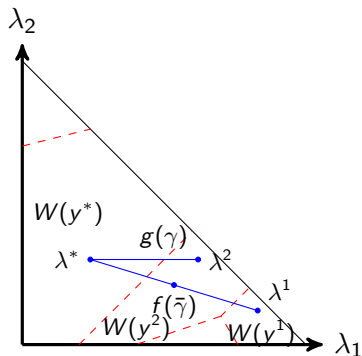
# Correctness and completeness of the algorithm

- Correctness: Algorithm visits only efficient solutions. ✓
- Completeness: Can cycles occur?



## Completeness of the algorithm

- Weight space:  $W(\bar{y}) = \{\lambda \in \mathbb{R}_+^k : \lambda^T \bar{y} \leq \lambda^T y \text{ for } y \in \mathcal{Y}\}$
- $W(\bar{y})$  convex
- Apply separation theorem for convex sets



$$\lambda \in \mathbb{R}_+^3, \lambda_1 + \lambda_2 + \lambda_3 = 1$$

**Thanks for your attention.**